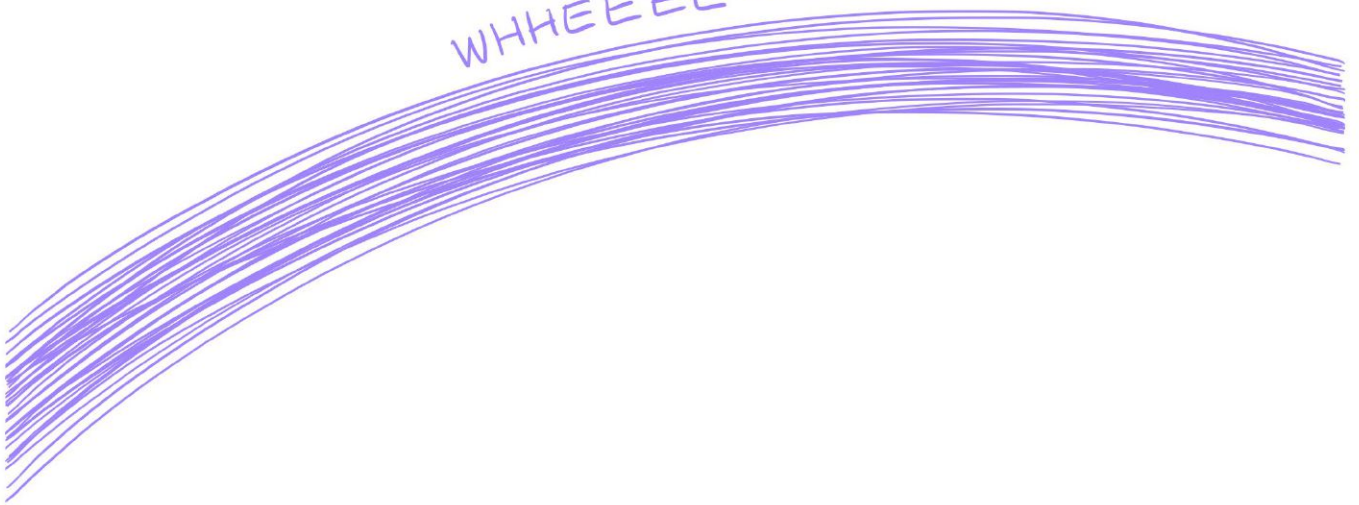


WHHEEE ~



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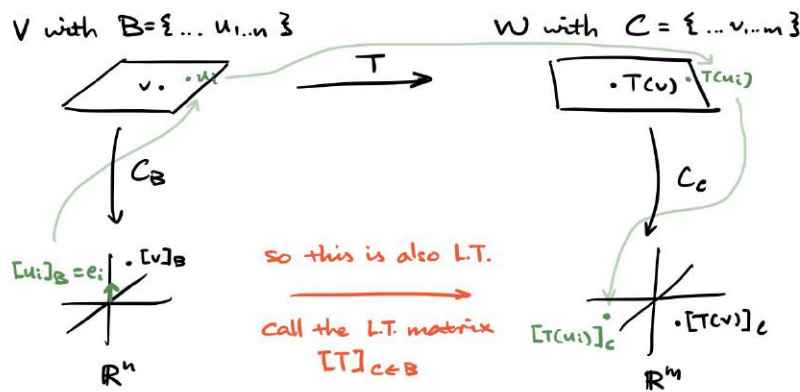
Recall coordinate vector

$$B = \{b_1, \dots, b_n\} \quad v = c_1 b_1 + \dots + c_n b_n \quad \longleftrightarrow \quad [v]_B = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix}$$

And

$$P_{C \leftarrow B} = \begin{bmatrix} | & & | \\ [b_1]_C & \dots & [b_n]_C \\ | & & | \end{bmatrix}$$

Choosing basis



→ Once again, we can just write where each standard basis vec land.

$$\text{So } [T]_{C \leftarrow B} = \begin{bmatrix} | & & | \\ [T(u_1)]_C & \dots & [T(u_n)]_C \\ | & & | \end{bmatrix}$$

Ex. $V = P_3$, $B = \{1, x, x^2, x^3\}$, $W = P_2$, $C = \{1, x, x^2\}$
 $D: P_3 \rightarrow P_2$ via $p(x) \mapsto p'(x)$.
 Find $[D]_{C \leftarrow B}$.

Well	$D(1) = 0$	so	$[D(1)]_C = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$
	$D(x) = 1$	so	$[D(x)]_C = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$
	$D(x^2) = 2x$	so	$[D(x^2)]_C = \begin{bmatrix} 0 \\ 2 \\ 0 \end{bmatrix}$
	$D(x^3) = 3x^2$	so	$[D(x^3)]_C = \begin{bmatrix} 0 \\ 0 \\ 3 \end{bmatrix}$

$$\text{So } [D]_{C \leftarrow B} = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

Ex. Projecting onto $l = \text{span}([0])$. Suppose $B=C=D = \{[0], [1]\}$

$$\begin{aligned} \text{Then } [proj_l]_{s \leftarrow s} &= \begin{bmatrix} [proj_l [0]]_s & [proj_l [1]]_s \end{bmatrix} \\ &= \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \end{aligned}$$