

### Measure Theory

$(\Omega, \mathcal{F}, P)$ ,  
 $\mathcal{P}: \mathcal{F} \rightarrow \mathcal{S}$ , usually  $\mathcal{S} = \{0, 1\}$   
 $\mathcal{F} \in \mathcal{P}(\Omega)$ , observable

Measure properties:  
 $P[\emptyset] = 0$   
 $P$  is  $\sigma$ -field  
 $\Omega, \phi \in \mathcal{F}$ ; closed under  $\setminus$  and countable  $\cup$   
 $A \subset B \Rightarrow P[A] \leq P[B]$   
 $A \subset B \Rightarrow P[A] < P[B]$  is monotone incr  
 $P[A \cup B] = P[A] + P[B] - P[A \cap B]$   
 If  $A, A_n \in \dots \in \mathcal{F}$ ,  
 $P[\bigcup A_n] = \lim P[A_n]$  "monotone conv."

Fact:  $\sigma$ -additivity  $\Rightarrow$  monotone cond.  
 Generating  $\sigma$ -field - infinite coin flip  
 $\mathcal{F} = \sigma(\{X_1, \dots, X_n\} \in \{0, 1\}^n | n \geq 1\}$

### Discrete Model

$\sum_{\omega \in \Omega} P[\{\omega\}] = 1$   
 $P_k = P[\{k\}]$   
 For unif. disjoint finite,  $P[A] = \frac{|A|}{|\Omega|}$

### Combinatorics

Choose size  $k$  subset from  $n$ :  
 $\binom{n}{k} = \frac{n!}{(n-k)!k!}$   
 For indistinguishable partitions, correction!  
 $\frac{1}{k!} \binom{n}{k_1, k_2, \dots, k_m}$

Choosing multiple distinguishable subsets  
 $\binom{n}{k_1, k_2} = \binom{n}{k_1} \binom{n-k_1}{k_2}$   
 $\binom{n}{k_1, k_2, \dots, k_m} = \frac{n!}{k_1! k_2! \dots k_m!}$  if  $\sum k_i = n$

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$T$  into  $4-1-1-1$ :  $\frac{1}{3!} \binom{4}{1, 1, 1, 1}$   
 RVs usually R  
 $X: \Omega \rightarrow \mathcal{S}$  discrete if  $\text{Im}(X)$  countable  
 $\leftarrow$  the input is random

Let  $G$  be a  $\sigma$ -field on  $\mathcal{S}$ ,  $G \in G$   
 $P[X \in G] = P[\{\omega | X(\omega) \in G\}]$   
 $= P[X^{-1}(G)]$   
 $= P \circ X^{-1}(G)$   
 $= \mu_X(G)$

Correlation  
 $\text{corr}(X, Y) = \frac{\text{cov}(X, Y)}{\sqrt{\text{var} X \text{var} Y}} \in [-1, 1]$   
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Moments  
 $k$ -th moment is  $E[X^k]$   
 $E[X^k] = \int X^k f(x) dx$   
 $L^k = \{X | X^k \text{ finite}\}$   
 Then if  $1 \leq q < p$  then  $L^p \subset L^q$   
 via  $L^q \subset L^p \subset L^r$  etc.

Use  $\varphi(\cdot) = |x|^{1/p}$ ,  $Y = |X|^p$   
 $E[|X|^{1/p}]^p \geq E[|X|^1]$   
 $|X_1|, |X_2|$

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### Independence

$A \perp B \Leftrightarrow P[A \cap B] = P[A]P[B]$   
 $\Leftrightarrow P[A|B] = P[A]$

R RVs  $X \perp Y \Leftrightarrow \forall A, B \in \mathcal{R}$ ,  $X \in A \perp Y \in B$   
 more generally  $P[\bigcap X_n \in A_n] = \prod P[X_n \in A_n]$

Expectation  
 $E[X] = \sum x P[X=x]$   
 $= \min_{b \in \mathcal{R}} (X-b)^+$   
 $= \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{k=1}^n X_k$   $X_n$  iid  $\rightarrow X$

Not every RV have E  
 If  $X$  is indicator,  $E[X] = P[X=1]$   
 $E[\cdot]$  is linear  
 $(\forall w, X(w) \geq Y(w)) \Rightarrow E[X] \geq E[Y]$   
 $E[\cdot]$  is monotone cont: let RVs  $0 \leq X_i \leq \dots$   
 suppose  $X_n \rightarrow X$ , then  $E[X] = \lim E[X_n]$

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### Conditional

Condition on  $B$ :  $\Omega' = B$   
 $F' = \{A \cap B | A \in \mathcal{F}\}$   
 $P_B(A) = \frac{P[A \cap B]}{P[B]}$

Write  $\int f(x) dx = \int \mu_X(dx)$   
 $E[g(X)] = \int g(x) \mu_X(dx)$   
 $\text{var} X = \int x^2 \mu_X(dx) - (E[X])^2$

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Discrete test intuition  
 Multiple tests assumed  
 indep w.r.t.  $P[\cdot|D]$   
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### Continuous Model

$X$  abs. cont.  $\Leftrightarrow \exists$  pdf  $f_X: \mathcal{R} \rightarrow \mathcal{R}^+$   
 $f_X \geq 0$   
 $\int_{\mathcal{R}} f_X(x) dx = 1$   
 $\forall B \in \mathcal{R}$ ,  $P[X \in B] = \int_B f_X(x) dx$

Write  $\int f(x) dx = \int \mu_X(dx)$   
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### Transformation

$Z(X, Y) = (U, V)$   
 bijective & differentiable  
 $Z[X] = \begin{bmatrix} U(X, Y) \\ V(X, Y) \end{bmatrix}$   
 $Z[V] = \begin{bmatrix} X(U, V) \\ Y(U, V) \end{bmatrix}$   
 $DZ = \frac{\partial Z(U, V)}{\partial X(U, V)} = \begin{bmatrix} \frac{\partial U}{\partial X} & \frac{\partial U}{\partial Y} \\ \frac{\partial V}{\partial X} & \frac{\partial V}{\partial Y} \end{bmatrix}$   
 $DZ^{-1} = \frac{\partial X(U, V)}{\partial X(U, V)} = \begin{bmatrix} \frac{\partial X}{\partial U} & \frac{\partial X}{\partial V} \\ \frac{\partial Y}{\partial U} & \frac{\partial Y}{\partial V} \end{bmatrix}$

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### Calculus

$\int u dv = uv - \int v du$   
 $\int x^2 dx = \frac{x^3}{3} + C$   
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### Brownian Motion

BM def:  
 $B_0 = 0$   
 $\forall 0 < t < \dots < t_n$   
 $D_t := B_{t_i} - B_{t_{i-1}}$  indep  
 $D_t \sim N(0, t - t_{i-1})$  - variance linear to time  
 $\forall w, B(w): t \rightarrow B_t(w)$  continuous

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